



香港中文大學  
The Chinese University of Hong Kong

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# Towards All-in-one Pre-training via Maximizing Multi-modal Mutual Information

Weijie Su\*, Xizhou Zhu\*, Chenxin Tao\*, Lewei Lu, Bin Li, Gao Huang,  
Yu Qiao, Xiaogang Wang, Jie Zhou, Jifeng Dai

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Presented By Weijie Su

# Large Vision Model Pre-training

Method & Model	Stage 1	Stage 2	Stage 3
SwinV2-G (3B) [a]	Masked Image Modeling <sub>pixel</sub>	Image Classification	-
BEiT-3 (2B) [b]	CLIP	Dense Distillation	Masked Data Modeling
FD-SwinV2-G (3B) [c]	Masked Image Modeling <sub>pixel</sub>	Image Classification	Dense Distillation

[a] Liu, Ze, et al. "Swin transformer v2: Scaling up capacity and resolution." CVPR 2022.

[b] Wang, Wenhui, et al. "Image as a foreign language: Beit pretraining for all vision and vision-language tasks." arXiv 2022.

[c] Wei, Yixuan, et al. "Contrastive learning rivals masked image modeling in fine-tuning via feature distillation." arXiv 2022.

**All** existing large vision model pre-training methods are **multi-stage**

# Problems of Multi-stage Pre-training

- **Difficult to Locate the Problematic Pre-training Stage** when the final performance is poor
- **Catastrophic Forgetting**
  - the linear classification accuracy of FD-DINO [1] in stage 2 (76.1) is worse than that of stage 1 (78.2)

Method	Backbone	res.	F. D.	IN-1K		ADE20K
				f.t.	linear	
BEiT [1]	ViT-B	224 <sup>2</sup>		83.2	37.6	47.1
MAE [17]	ViT-B	224 <sup>2</sup>		83.6	68.0	48.1
SimMIM [45]	ViT-B	224 <sup>2</sup>		83.8	56.7	47.6
SimMIM [45]	Swin-B	224 <sup>2</sup>		84.8	24.8	48.3
WiSE-FT CLIP [40]	ViT-L	336 <sup>2</sup>		87.1	-	-
DINO [3]	ViT-B	224 <sup>2</sup>		82.8	78.2	46.2
FD-DINO	ViT-B	224 <sup>2</sup>	✓	<b>83.8</b> (+1.0)	76.1	<b>47.7</b> (+1.5)

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Our Solution: all-in-one single-stage pre-training under an unified perspective

## All-in-One: M3I Pre-training



training sample  
input transform  
target transform

$$(s, t_x, t_y) \sim D_{\text{train}}$$

$$x = t_x(s), y = t_y(s)$$

$$z_x \sim p(z_x|x), z_y \sim p(z_y|y) \quad (\text{encoded training representation}),$$

(sampled training sample),

(extracted training data),

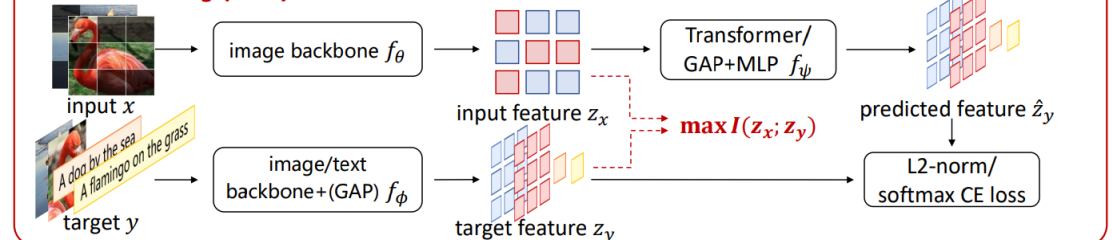
$$I(z_x; z_y | t_x, t_y) = \mathbb{E}_{p(t_y)} [H(p(z_y|t_y))]$$

regularization term to avoid collapse

$$- \mathbb{E}_{p(s, t_x, t_y, z_x)} [H(p(z_y|y), p(z_y|z_x, t_x, t_y))], \quad (1)$$

(cross-entropy) prediction term for target representation

## M3I Pre-training (ours)



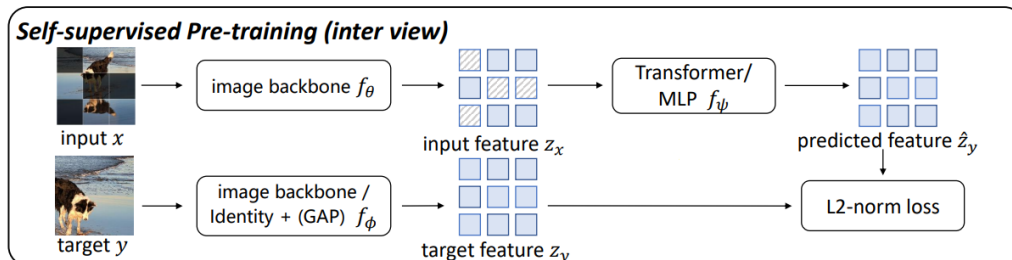
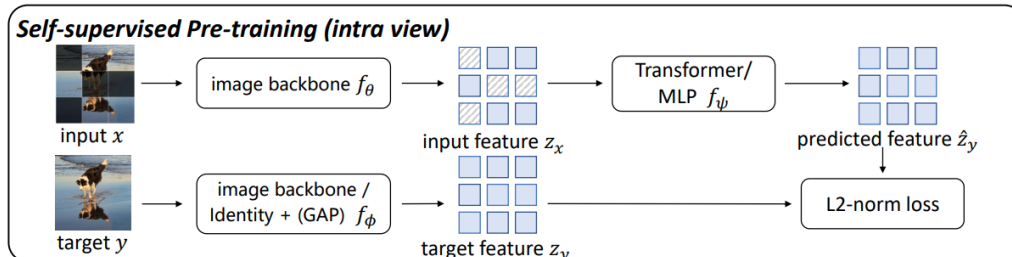
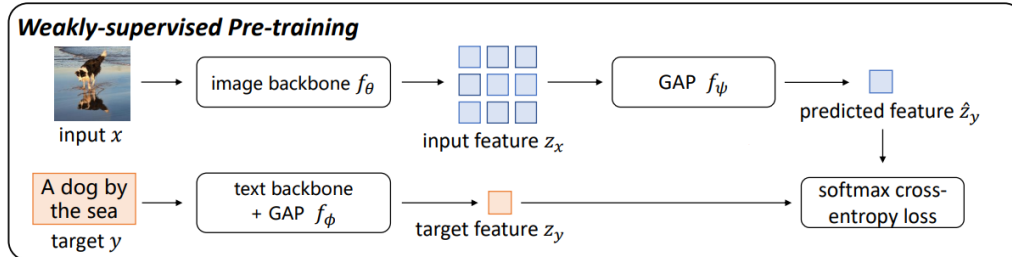
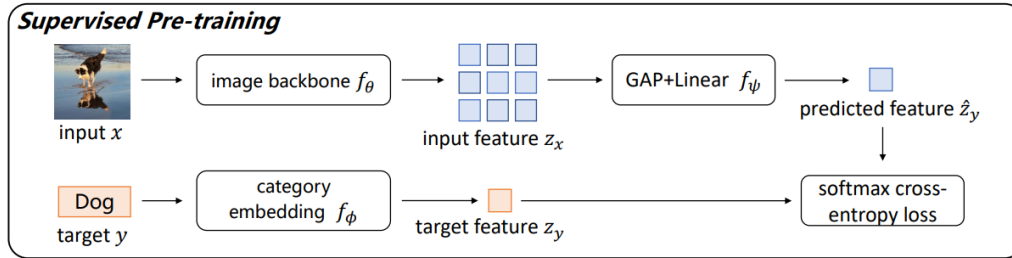
# M3I Pre-training – Result on 1B model

Pre-training Approach	Model	Pipeline	Public Data	Private Data	ImageNet val	COCO test-dev	LVIS minival	ADE20k val
M3I Pre-training	InternImage-H [78] (1B)	Single Stage: M3I Pre-training	427M image-text 15M image-category	-	89.2	<b>65.4</b>	<b>62.5</b>	<b>62.9</b>
[47]	SwinV2-G (3B)	Stage 1: Masked Image Modeling <sub>pixel</sub> Stage 2: Image Classification	15M image-category	55M image-category	89.2	63.1	-	59.9
[77]	BEiT-3 (2B)	Stage 1: CLIP Stage 2: Dense Distillation Stage 3: Masked Data Modeling	21M image-text 15M image-category	400M image-text	<b>89.6</b>	63.7	-	62.8
[80]	SwinV2-G (3B)	Stage 1: Masked Image Modeling <sub>pixel</sub> Stage 2: Image Classification Stage 3: Dense Distillation	15M image-category	55M image-category	89.4	64.2	-	61.4
† previous best					89.1 <sup>a</sup>	64.5 <sup>b</sup>	59.8 <sup>c</sup>	60.8 <sup>d</sup>

† previous best results on these tasks with only public training data. Results reference: a. MOAT, b. Group DETR v2, c. GLIPv2, d. Mask DINO

Achieves SoTA performance on various benchmarks in public-data only setting

# 4 Types of Visual Pre-training Methods

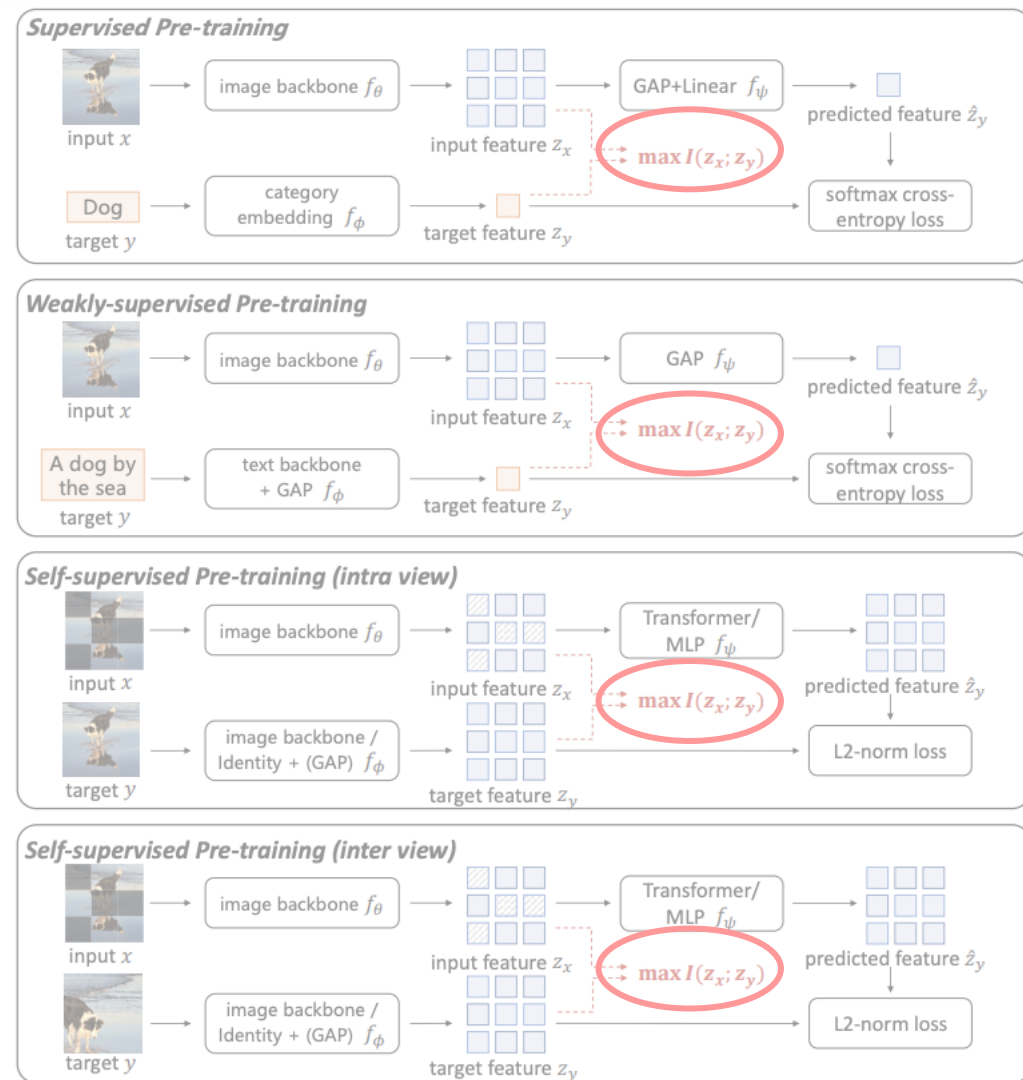




# Unified Framework: Maximizing Mutual Information



# Unified Framework: Maximize Mutual Information



training sample  $s$   
input transform  $t_x$   
target transform  $t_y$

$$(s, t_x, t_y) \sim D_{\text{train}}$$

$$x = t_x(s), y = t_y(s)$$

$$z_x \sim p(z_x|x), z_y \sim p(z_y|y)$$

(sampled training sample),

(extracted training data),

(encoded training representation),

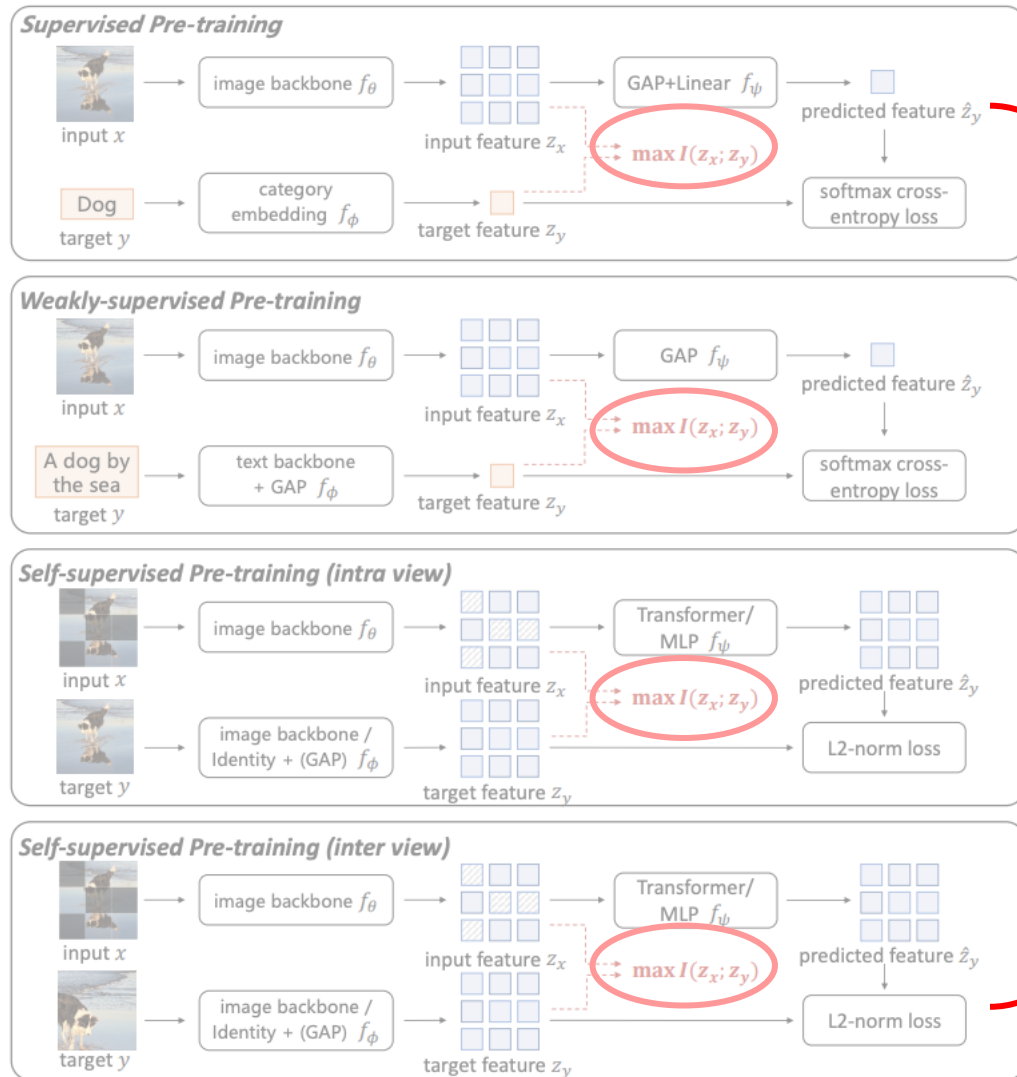
$$I(z_x; z_y | t_x, t_y) = \mathbb{E}_{p(t_y)} [H(p(z_y|t_y))]$$

regularization term to avoid collapse

$$- \mathbb{E}_{p(s, t_x, t_y, z_x)} [H(p(z_y|y), p(z_y|z_x, t_x, t_y))], \quad (1)$$

(cross-entropy) prediction term for target representation

## All-in-One: M3I Pre-training

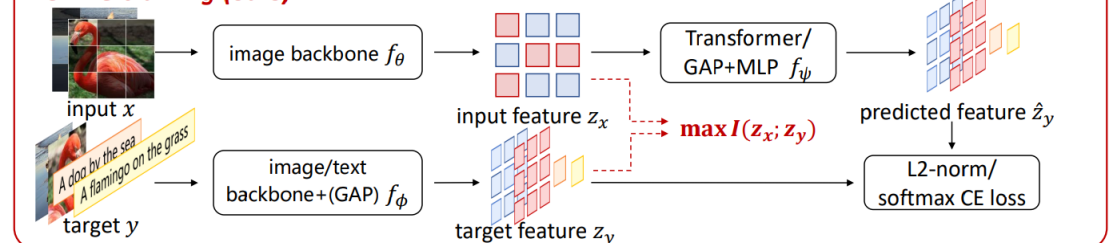


training sample  
input transform  
target transform

$(s, t_x, t_y) \sim D_{\text{train}}$  (sampled training sample),  
 $x = t_x(s), y = t_y(s)$  (extracted training data),  
 $z_x \sim p(z_x|x), z_y \sim p(z_y|y)$  (encoded training representation),

$$I(z_x; z_y | t_x, t_y) = \underbrace{\mathbb{E}_{p(t_y)} [H(p(z_y|t_y))]}_{\text{regularization term to avoid collapse}}$$

$$- \underbrace{\mathbb{E}_{p(s, t_x, t_y, z_x)} [H(p(z_y|y), p(z_y|z_x, t_x, t_y))]}_{\text{(cross-entropy) prediction term for target representation}}, \quad (1)$$

**M3I Pre-training (ours)**

# Unified Framework: All Instantiations

Pre-training Method	Typical Work	Input Data $x$	Target Data $y$	Input Representation $z_x$	Target Representation $z_y$	Regularization $H(p(z_y t_y))$	Distribution Form $\hat{P}$
<i>Supervised Pre-training :</i>							
Image Classification	ViT [24]	view1	category	dense feature	category embedding	negative categories	Boltzmann
<i>Weakly-supervised Pre-training :</i>							
Contrastive Language-Image Pre-training	CLIP [55]	view1	text	dense feature	text embedding	negative texts	Boltzmann
<i>Self-supervised Pre-training (intra-view) :</i>							
Auto-Encoder	-	view1	view1	dense feature	dense pixels	-	Gaussian
<sup>1</sup> Dense Distillation	FD [80],BEiT v2 tokenizer [54]	view1	view1	dense feature	dense feature	stop gradient	Gaussian
Global Distillation	-	view1	view1	dense feature	global feature	stop gradient	Boltzmann
Masked Image Modeling <sub>pixel</sub>	MAE [30]	masked view1	view1	dense feature	dense pixels	-	Gaussian
<sup>2</sup> Masked Image Modeling <sub>feature</sub>	data2vec [4],MILAN [35], BEiT [5],BEiT v2 [54]	masked view1	view1	dense feature	dense feature	stop gradient	Gaussian
Masked Image Modeling <sub>global</sub>	-	masked view1	view1	dense feature	global feature	stop gradient	Gaussian
<i>Self-supervised Pre-training (inter-view) :</i>							
Novel View Synthesis	-	view2	view1	dense feature	dense pixels	-	Gaussian
Dense Instance Discrimination	DenseCL [79]	view2	view1	dense feature	dense feature	negative samples	Boltzmann
<sup>3</sup> Instance Discrimination	MoCo [31],BYOL [27], Barlow Twins [89]	view 2	view1	dense feature	global feature	negative samples / stop gradient / decorrelation	Boltzmann / Gaussian
Siamese Image Modeling <sub>pixel</sub>	-	masked view2	view1	dense feature	dense pixels	-	Gaussian
Siamese Image Modeling <sub>feature</sub>	SiameseIM [67]	masked view2	view1	dense feature	dense feature	stop gradient	Gaussian
Siamese Image Modeling <sub>global</sub>	MSN [3]	masked view2	view1	dense feature	global feature	negative samples	Boltzmann

# Unified Framework: All Instantiations

Pre-training Method	Typical Work	Input Data $x$	Target Data $y$	Input Representation $z_x$	Target Representation $z_y$	Regularization $H(p(z_y t_y))$	Distribution Form $\hat{P}$
<i>Supervised Pre-training :</i>							
Image Classification	ViT [24]	view1	category	dense feature	category embedding	negative categories	Boltzmann
<i>Weakly-supervised Pre-training :</i>							
Contrastive Language-Image Pre-training	CLIP [51]	view1	text	dense feature	text embedding	negative texts	Boltzmann
<i>Self-supervised Pre-training (intra-view) :</i>							
Auto-Encoder	-	view1	view1	dense feature	dense pixels	-	Gaussian
<sup>1</sup> Dense Distillation	FD [80], BEiT v2 tokenizer [54]	view1	view1	dense feature	dense feature	stop gradient	Gaussian
Global Distillation	-	view1	view1	dense feature	global feature	stop gradient	Boltzmann
Masked Image Modeling <sub>pixel</sub>	MAE [30]	masked view1	view1	dense feature	dense pixels	-	Gaussian
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Masked Image Modeling <sub>global</sub>	-	masked view1	view1	dense feature	global feature	stop gradient	Gaussian
<i>Self-supervised Pre-training (inter-view) :</i>							
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Siamese Image Modeling <sub>feature</sub>	SiameseIM [67]	masked view2	view1	dense feature	dense feature	stop gradient	Gaussian
Siamese Image Modeling <sub>global</sub>	MSN [3]	masked view2	view1	dense feature	global feature	negative samples	Boltzmann

12 SSP Methods, some of which have not been explored as pre-training before

# Compare 12 SSP Methods

Pre-training Method	Input Data $x$	Target Representation $z_y$	ImageNet Top1	COCO AP <sup>box</sup>
<i>Self-supervised Pre-training (intra-view)</i>				
(a) Auto-Encoder	view1	dense pixels	77.5	0.0 <sup>†</sup>
(b) Dense Distillation	view1	dense feature	78.8	32.4
(c) Global Distillation	view1	global feature	77.1	27.9
(d) Masked Image Modeling <sub>pixel</sub>	masked view1	dense pixels	83.1	46.8
<b>(e) Masked Image Modeling<sub>feat</sub></b>	<b>masked view1</b>	<b>dense feature</b>	<b>83.3</b>	<b>47.4</b>
(f) Masked Image Modeling <sub>global</sub>	masked view1	global feature	83.2	47.5
<i>Self-supervised Pre-training (inter-view)</i>				
(g) Novel View Synthesis	view2	dense pixels	78.8	33.0
(h) Dense Instance Discrimination	view2	dense feature	83.2	50.1
(i) Instance Discrimination	view2	global feature	83.0	46.4
(j) Siamese Image Modeling <sub>pixel</sub>	masked view2	dense pixels	78.9	38.1
<b>(k) Siamese Image Modeling<sub>feat</sub></b>	<b>masked view2</b>	<b>dense feature</b>	<b>83.7</b>	<b>49.8</b>
(l) Instance Discrimination <sub>mask</sub>	masked view2	global feature	82.9	46.2

# Multi-Input Multi-target

$$\begin{aligned}
 (\mathbf{s}, \mathbf{t}_x, \mathbf{t}_y, X, Y) &\sim D_{\text{train}} && \text{(sample inputs and targets)} \\
 \mathbf{z}_x &= f_{\theta}(X = \{x_i\}_{i=1}^N) && \text{(encode multiple inputs jointly)} \\
 \mathbf{z}_y^k &= f_{\phi_k}(Y_k), Y_k = \{y_{kj}\}_{j=1}^{M_k} && \text{(encode multiple targets separately)} \\
 \hat{\mathbf{z}}_y^k &= f_{\psi_k}(\mathbf{z}_x, \mathbf{t}_x, \mathbf{t}_y) && \text{(predict multiple targets separately)}
 \end{aligned}$$

$$I(\mathbf{z}_x; \{\mathbf{z}_y^k\}_{k=1}^K | \mathbf{t}_x, \mathbf{t}_y) \geq \sup_{\{f_{\psi_k}\}_{k=1}^K} \underbrace{\mathbb{E}_{p(\mathbf{t}_y)} \left[ H\left(p(\{\mathbf{z}_y^k\}_{k=1}^K | \mathbf{t}_y)\right) \right]}_{\text{regularization term to avoid collapse}}$$

$$+ \underbrace{\sum_{k=1}^K \mathbb{E}_{p(\mathbf{s}, \mathbf{t}_x, \mathbf{t}_y)} \left[ \log \hat{P}_k(\mathbf{z}_y^k | \hat{\mathbf{z}}_y^k) \right]}_{\text{(log-likelihood) prediction term for target representation}},$$

$$\Rightarrow L(\mathbf{s}, \mathbf{t}_x, \mathbf{t}_y) = \sum_{k=1}^K -\log \hat{P}_k(\mathbf{z}_y^k(\phi_k) | \hat{\mathbf{z}}_y^k(\theta, \psi_k)), \quad (4)$$

## Ablation of Multi-Target

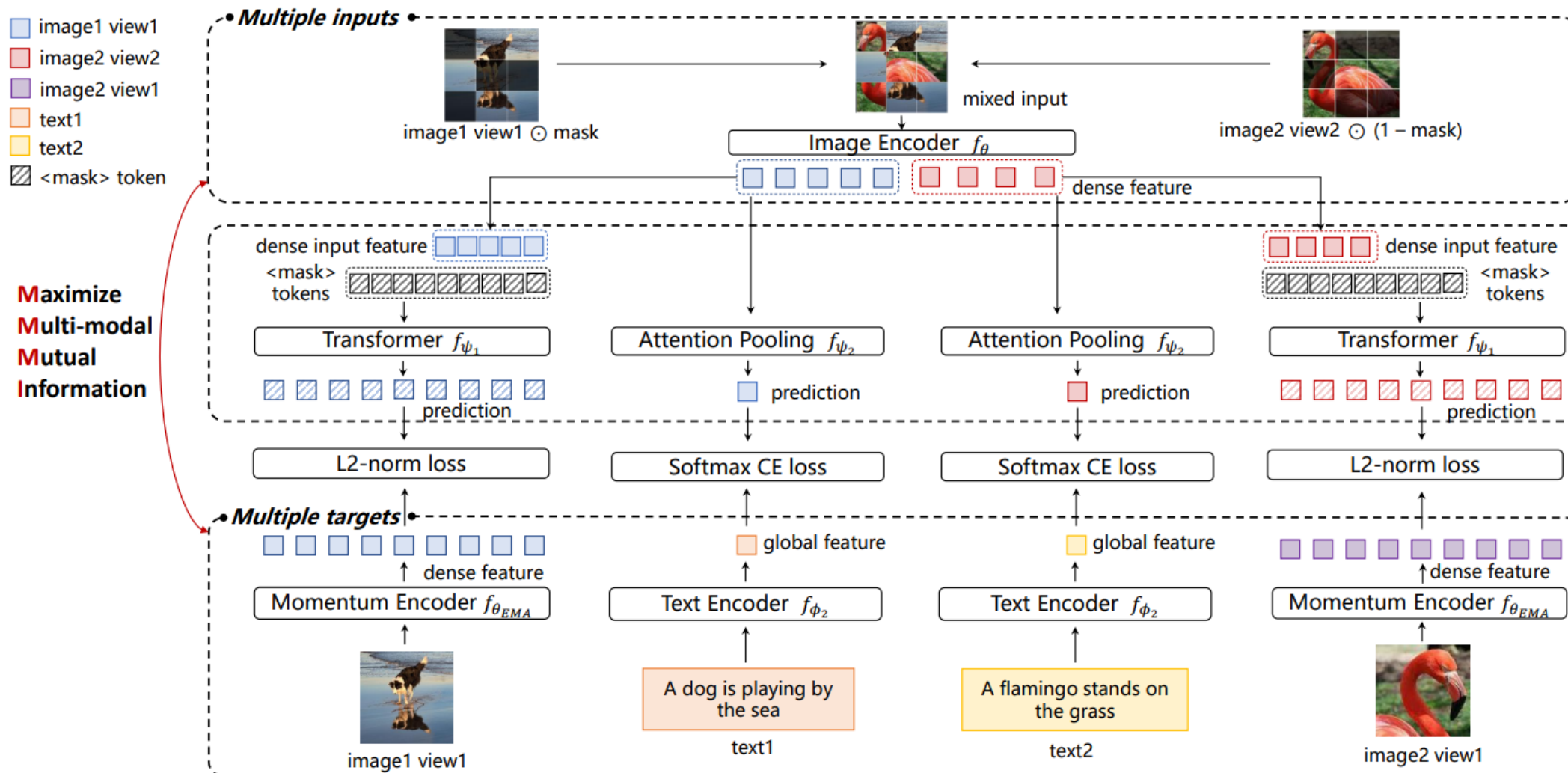
Pre-training Method	ImageNet	COCO	LVIS		ADE20k
	Top1	AP <sup>box</sup>	AP <sup>box</sup>	AP <sup>box</sup> <sub>rare</sub>	mIoU
Image Classification	81.8	46.6	33.0	25.5	45.1
Best Intra-view SSP	83.3	47.4	31.2	21.9	40.1
Best Inter-view SSP	83.7	49.8	35.2	26.9	47.7
<i>Ours</i>					
M3I Pre-training w/o mix	83.7	50.3	36.6	27.2	48.7
<b>M3I Pre-training</b>	<b>83.9</b>	<b>50.8</b>	<b>37.5</b>	<b>29.6</b>	<b>49.0</b>



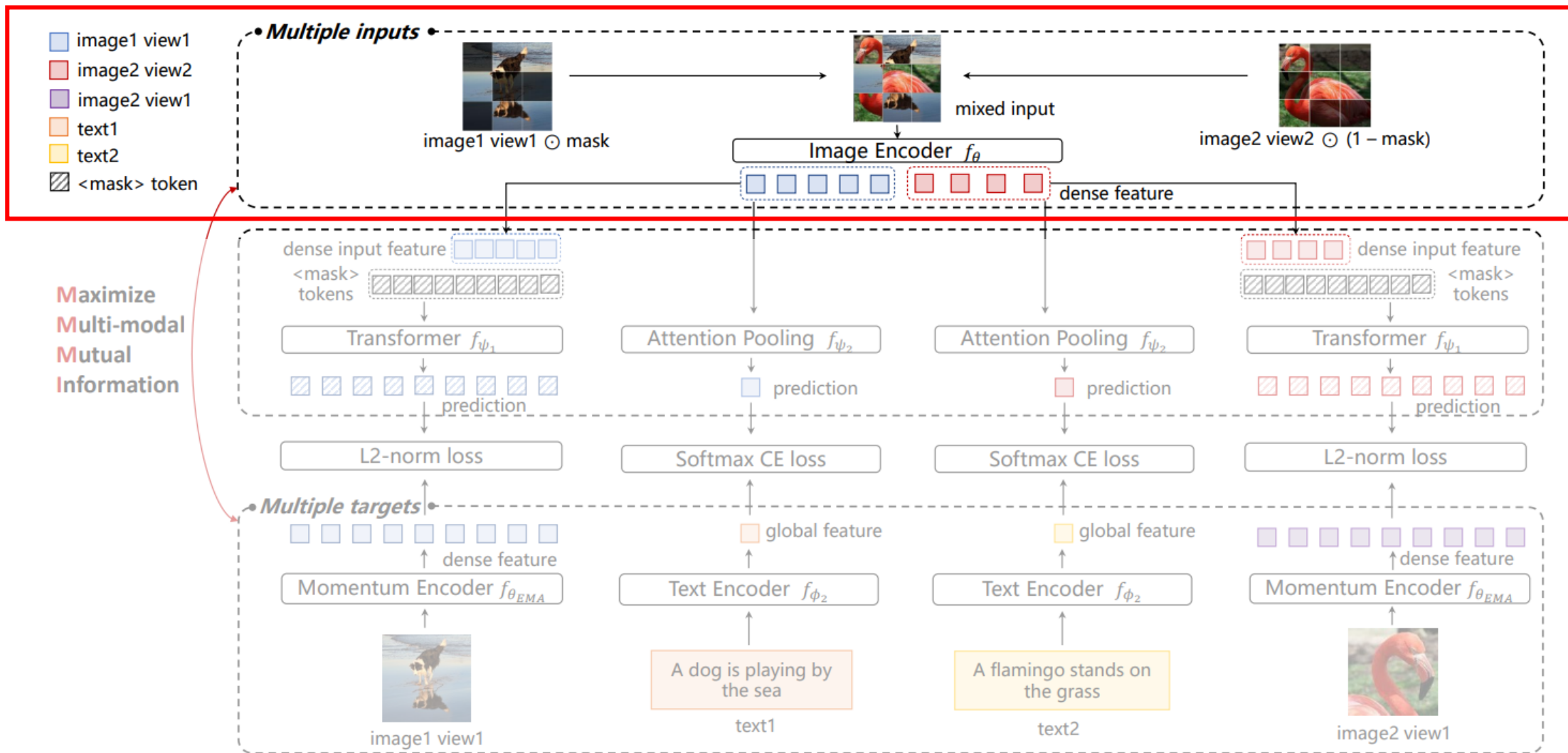
## Ablation of Multi-Input

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	Top1	AP <sup>box</sup>	AP <sup>box</sup>	AP <sup>box</sup> <sub>rare</sub>	mIoU
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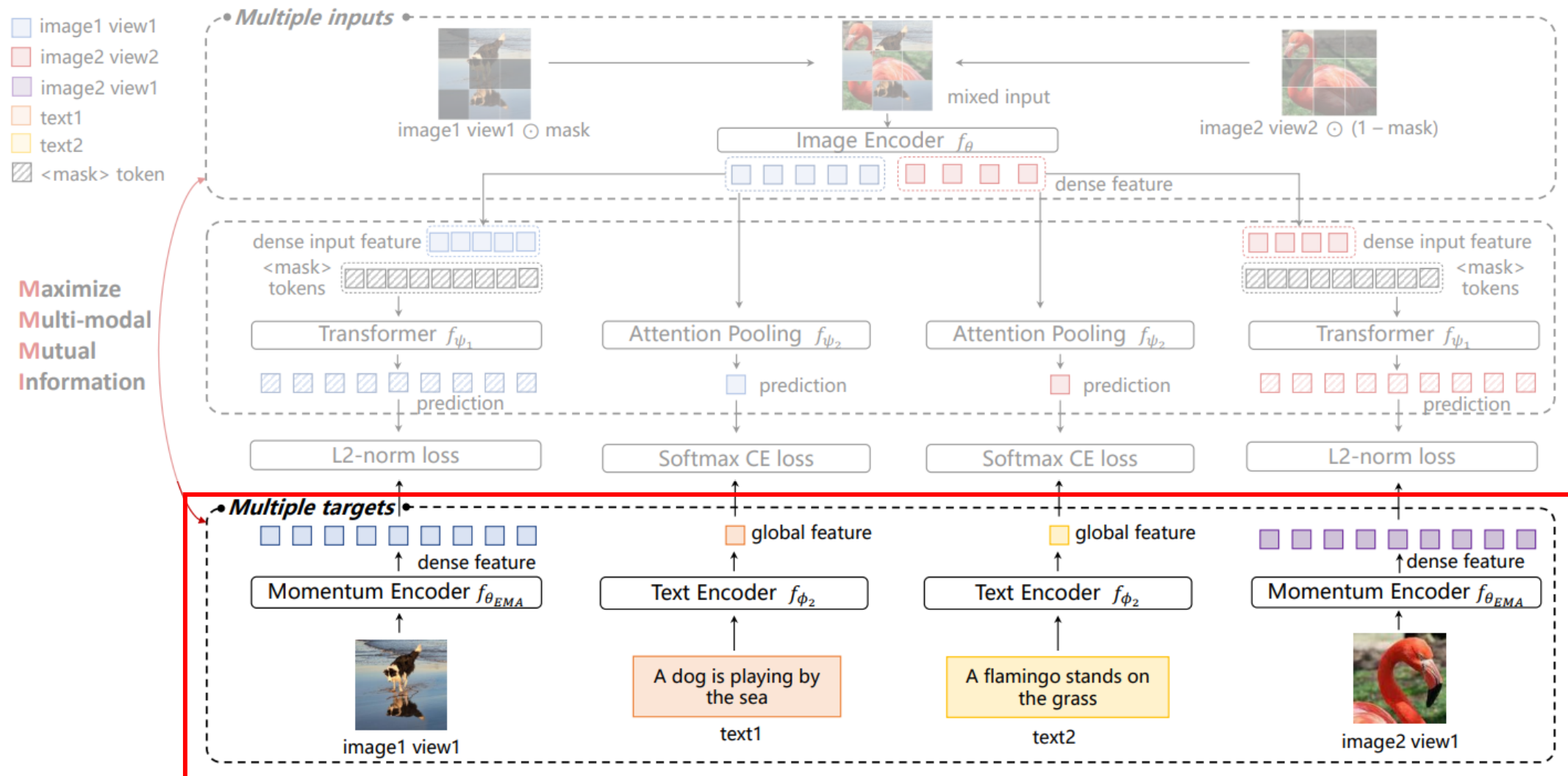
# M3I Pre-training



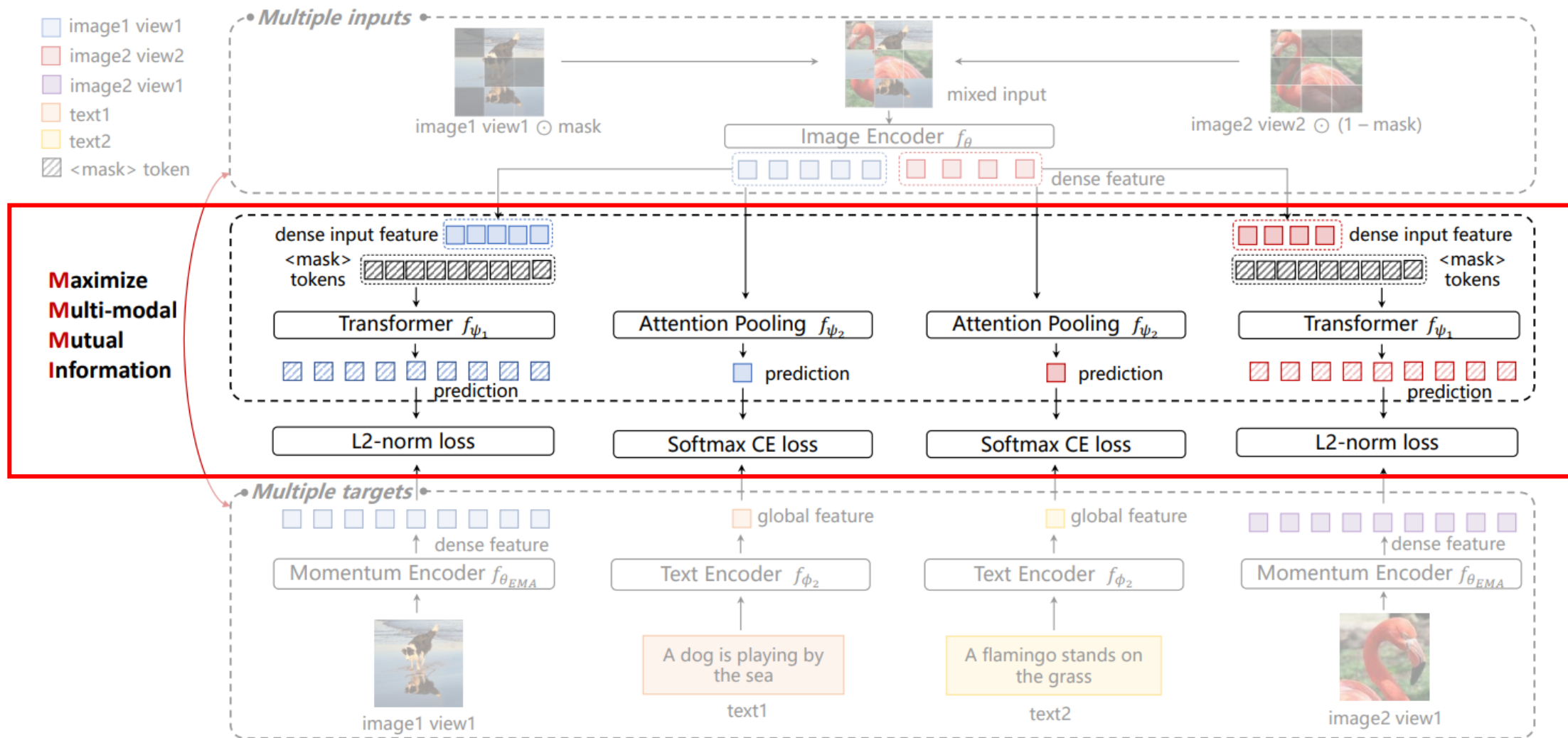
# M3I Pre-training



# M3I Pre-training



# M3I Pre-training



## Result on InternImage-H (1B)

Pre-training Approach	Model	Pipeline	Public Data	Private Data	ImageNet val	COCO test-dev	LVIS minival	ADE20k val
M3I Pre-training	InternImage-H [78] (1B)	Single Stage: M3I Pre-training	427M image-text 15M image-category	-	89.2	<b>65.4</b>	<b>62.5</b>	<b>62.9</b>
[47]	SwinV2-G (3B)	Stage 1: Masked Image Modeling <sub>pixel</sub> Stage 2: Image Classification	15M image-category	55M image-category	89.2	63.1	-	59.9
[77]	BEiT-3 (2B)	Stage 1: CLIP Stage 2: Dense Distillation Stage 3: Masked Data Modeling	21M image-text 15M image-category	400M image-text	<b>89.6</b>	63.7	-	62.8
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† previous best					89.1 <sup>a</sup>	64.5 <sup>b</sup>	59.8 <sup>c</sup>	60.8 <sup>d</sup>

† previous best results on these tasks with only public training data. Results reference: a. MOAT, b. Group DETR v2, c. GLIPv2, d. Mask DINO

Achieves SoTA performance on various benchmarks in public-data only setting

## Result on ViT-B

Task	Metric	ImageNet Pre-train			M3I (ImageNet)	YFCC Pre-train	
		SSP (intra-view)	SSP (inter-view)	SP		WSP	M3I (YFCC)
ImageNet w/o Fine-tuning	Top1 acc.	×	×	<b>83.8</b> (DeiT-III)	83.3	<sup>†</sup> 37.6 (CLIP)	<sup>†</sup> 39.1
ImageNet Linear Classification	Top1 acc.	79.5 (iBOT)	78.0 (SiameseIM)	<b>83.8</b> (DeiT-III)	<b>83.8</b>	66.5 (CLIP)	72.3
ImageNet Fine-tuning	Top1 acc.	<b>84.2</b> (data2vec)	84.1 (SiameseIM)	83.8 (DeiT-III)	<b>84.2</b>	80.5 (CLIP)	83.7
COCO	AP <sup>box</sup>	51.6 (MAE)	52.1 (SiameseIM)	47.6 (Sup.)	<b>52.2</b>	-	51.9
LVIS	AP <sup>box</sup>	40.1 (MAE)	40.5 (SiameseIM)	37.2 (Sup.)	40.6	-	<b>40.8</b>
	AP <sup>box</sup> <sub>rare</sub>	38.1 (MAE)	38.1 (SiameseIM)	-	38.2	-	<b>38.4</b>
ADE20k	mIoU	50.0 (iBOT)	51.1 (SiameseIM)	49.3 (DeiT-III)	<b>51.3</b>	-	<b>51.3</b>

M3I Pretraining can maintain all desired properties through a single-stage pre-training

# Conclusion

- Multi-stage pre-training methods has several problems
- We proposed a generic pre-training framework that unifies mainstream pre-training approaches
- We proposed an single-stage all-in-one pre-training method, M3I Pre-training
- Our approach surpasses previous pre-training methods in various transfer-learning settings

**Poster ID:** WED-PM-337

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Paper



Code